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Cavitation bubbles: a tracer for turbulent mixing in large rivers

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ABSTRACT: On the Seine river in Paris, the high frequency of tourist boats traffic may exert a significant impact on transport of sediments and thus on transport and residence time of pollutants. To have a better understanding of anthropogenic effects and more generally to study rivers suspended sediments dynamics, it is essential to quantify the river transport capacity. Turbulent mixing is one of these transport mechanisms and we present here a simple technique to estimate lateral coefficient using ADCP backscatter signal analysis. We realized several static measurements during low water discharge ($Q = 140$ cubic meters per second) in which we can see a strong correlation between high backscatter values and the passage of boats. We argue that these high backscatter values, in the center of Paris city, are not due to a sediment plume but to cavitation bubbles. These high values suggest that resonant, ~ 10 micron bubbles are present in the flow in agreement with LISST grain size measurements. Given their slow ascent velocity these particles can be used as passive markers to estimate the lateral turbulent mixing coefficient. For this purpose we develop a dimensionless form of the sonar equation that, when coupled to a simple lateral turbulent diffusion model, allows to compute lateral diffusion coefficients. These estimates of lateral diffusion coefficient have an important implication for representative river water sampling and can be very useful to calibrate numerical models of river flow and sediment transport.

1 INTRODUCTION

The Seine river, in Paris city (Fig.1), is subject to effects of human activities like channel enlargement and dam regulation of water level to allow navigation even during low water discharge period. This navigation, especially the high frequency turnover of tourist boats disturbs the transport of sediments. In order to study its impact on natural flow processes we develop a measurement protocol to study fluvial dynamic along river cross-sections. Turbulent mixing plays an important role and estimation of the lateral turbulent dispersion rate is essential to better understand sediment transport. Unfortunately these estimations are still scarce because they involve deployment of measurement techniques such as dye tracers (Fischer & Park, 1967), that are difficult to apply on large rivers. More recently Bouchez et al. (Bouchez et al., 2010) used an isotopic method to estimate lateral turbulent mixing rate in Amazon river using two tributaries with distinct chemical signatures. In this contribution we apply an original technique to achieve this estimation using an Acoustic Doppler Current Profiler (ADCP).

We here describe measurement setup and present results of granulometric and echo backscatter data acquired in April 2010 in which we can infer the presence of bubbles. We then discuss echo backscatter processing, in order to get a dimensionless concentration, and develop a simple 1D depth-averaged lateral turbulent mixing model. Finally an application of this model is performed to estimate a coefficient of lateral turbulent mixing.

2 FIELD MEASUREMENTS SETUP AND DATA

To measure river currents and to study particle dynamics we setup an experimental device (Fig. 1) composed of two main instruments: an ADCP (Rio Grande 1200 kHz from RD-Instrument) and a LISST

(Laser In Situ Scattering and Transmissometry, LISST-25 from Sequoia). We realised synchronous measurements from a static location established using a rope from a bridge to stabilize an inflatable boat. These measurements have been made at Sully bridge in the center of Paris city, where tourist boats pass one by one and only in one way leading to more comprehensible backscatter signal.

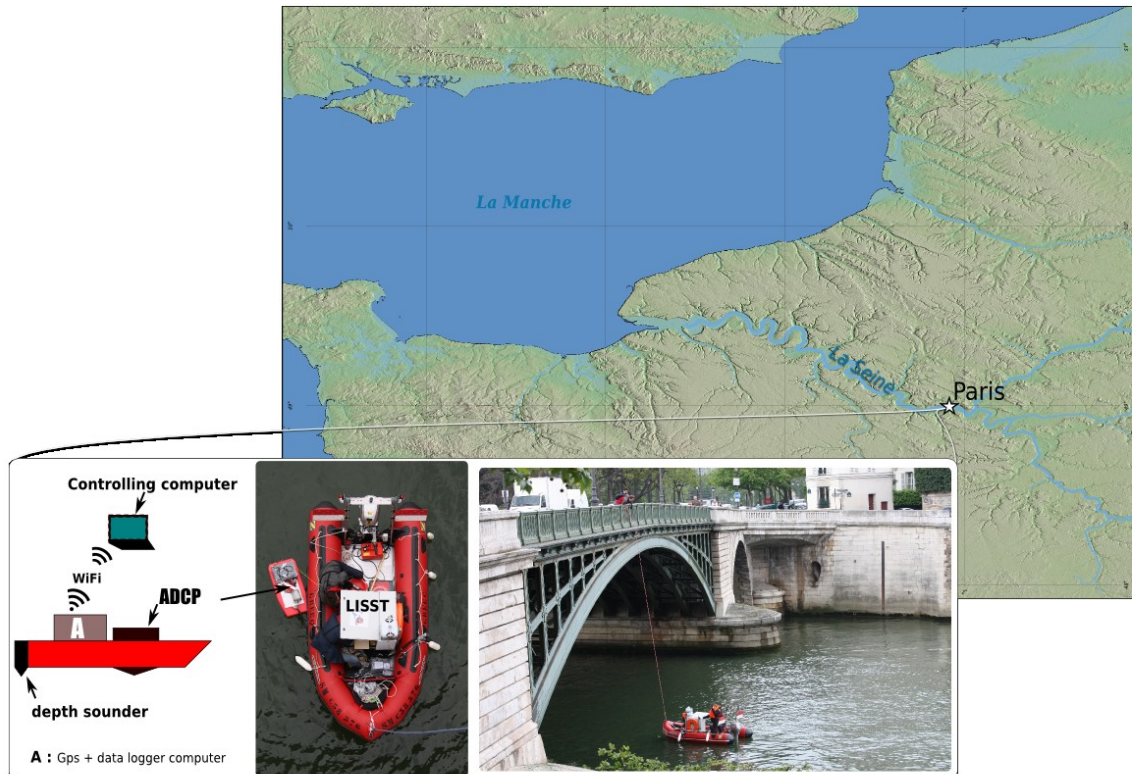


Figure 1 Location of the present study and experimental devices setup

ADCP instruments use the Doppler shift effect to calculate the velocity field and record the echo backscatter over the entire water column within bin in the size range of 5 to 25 centimeter (Gordon, 1996). This instrument is becoming widely used in rivers to estimate their discharges using moving-vessel (Yorke & Oberg, 2002). Using it from a fixed location allow to record time series of velocity field (Muste et al., 2004) and backscatter. The latter reflect the amount of sound reflectors (particles) present in the insonified volume for each bins. It is generally used to estimate suspended solid concentration to study sediment dynamic. This estimation is not straightforward and require independent concentration measurements, like optical backscatter point sensor (OBS) (Gartner, 2004; Hoitink & Hoekstra, 2005) or direct sample measurements (Holdaway et al., 1999), in order to calibrated echo backscatter. In this study we use a LISST to complete backscatter measurements.

The LISST is an optical instrument that calculates the concentration of particles for different particle sizes using their light scattering properties (Agrawal & Pottsmith, 2000). It gives access to grain size distribution for a given depth. The LISST-StreamSide measures particle sizes in 32 log-spaced size classes in the size range of 1.25 to 250 microns. Both of these measurements are sensible to any kind of reflectors like air bubbles or organic organisms so a particular attention has to be payed during measurements in river especially if there is ship traffic.

On backscatter time series recorded during this study, strong variations of backscatter are present (right of Fig.2) and seems to be correlated with ship passages. This kind of backscatter shape can be due to sediment plume or cavitation bubbles produced by ships propellers. Looking at particle size distribution measured with the LISST during one of this high backscatter stage, presented on left of Fig.2, we can remark the presence of 10 micron sized particles. For our ADCP transmitted sound pulses frequency (1200 kHz), this size of particles corresponds to resonant radius for air bubbles (Brennen, 1995). Furthermore concentrations measured with the LISST are small while backscatter variations are relatively important, reflecting a greater sensitivity to presence of bubbles for the ADCP.

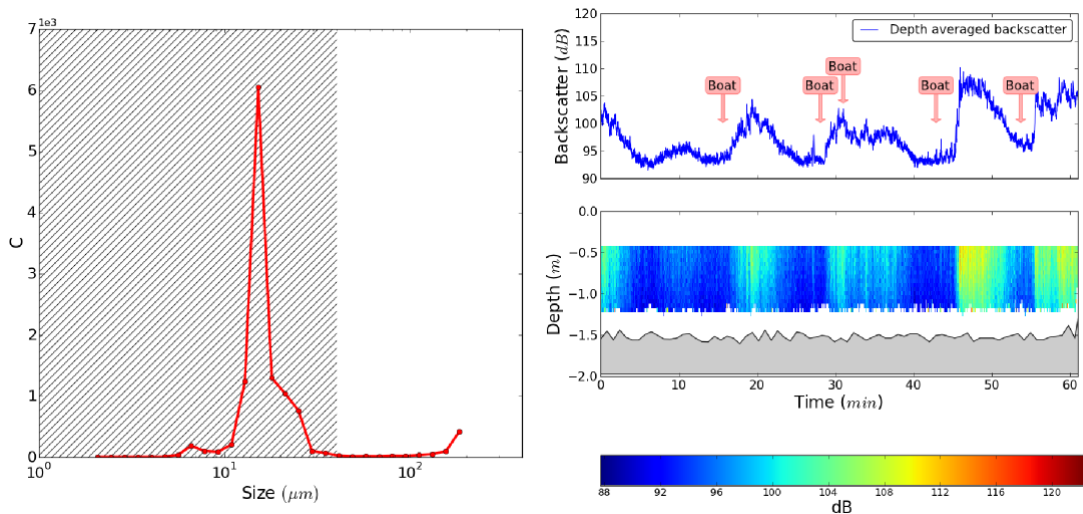


Figure 2 Left: Particle size distribution from LISST measurement, hashed zone represent bubble resonant radius for frequency of our ADCP (1200 kHz). Right: Backscatter time series recorded at Sully bridge, on bottom the raw ADCP backscatter with respect to time and depth and on top the depth-averaged backscatter

Ship propellers are known to produce micron sized bubbles by cavitation present up to a depth of twice the draft of ship (Miner, 1986). By looking at the shape of recorded backscatter signal with respect to depth and time we can assume that particles have a slow ascending movement. Observations of ship's wake have been performed by Marmorino and Trump (Marmorino & Trump, 1996) who used an original technique based on a 600 kHz ADCP in horizontal position and looking toward the ship's wake. In their measurements strong increases in backscatter values are cause by bubbles induced by ship propellers. Finally looking at aerial pictures, we observe the presence of bubbles only inside Paris, whereas boats outside the center of Paris produce bubbles and sediment plume (Fig.3). These observations put together suggest that, in our measurements, we are in presence of bubbles.

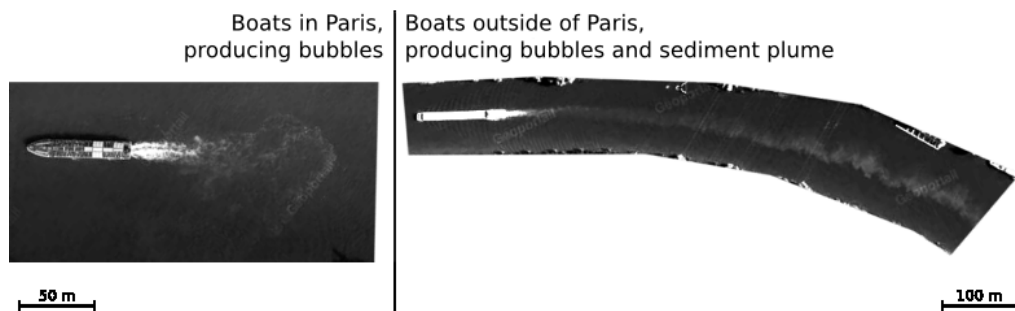


Figure 3 Aerial images (from IGN) showing presence of sediment plume for a boat outside of Paris, on right, and a tourist boat inside Paris producing only bubbles, on left. (© GEOPORTAIL)

The backscatter record (right of Fig.2) is characterised by a rapid increase of his intensity just after boat passages, then it slightly decrease up to a base level (~ 93 dB). This shape is characteristic of diffusive processes and we can use this bubbles as a tracer to quantify lateral turbulent mixing coefficient. Here, direct calibration, converting backscatter into concentrations, can not be performed because LISST response to bubbles is not well correlated to backscatter variations. In order to use it to estimate the lateral turbulent diffusion we use a dimensionless equation which allow to access to a concentration ratio.

3 BACKSCATTER PROCESSING

Backscatter recorded by ADCP needs to be converted from "counts" to decibel (dB) taking into account geometrical effect of transducers and transmission loss due to water and sometimes particles (Gartner,

2004). The base of the theory is defined by a simplified form of the sonar equation (Urlick, 1975) which can be written as:

$$RL = SL - 2TL + TS \quad (1)$$

where SL is the source level that can be computed from battery voltage only if a calibration have been performed. RL is the reverberation level which relies echo intensity recorded by ADCP for each bins in "counts" to dB using $RL=K_c RS$, where RS is the relative signal strength and K_c is a conversion factor, here taken to manufacturer value 0.45 dB/counts (Deines, 1999). The term $2TL$ is the two ways transmission loss expressed like:

$$2TL = 20\log_{10}(\Psi R) + 2\alpha_w R \quad (2)$$

with R the slant distance from transducer to bin, Ψ the near-field correction which is a function of R (Downing et al., 1995) and α_w the water absorption (Francois & Garrison, 1982). Finally the term TS of equation 1 is the target strength linked to particle sound reflection properties and concentration (Thorne & Hanes, 2002; Tessier, 2006):

$$TS = 10\log_{10}\left(C \frac{\sigma}{\rho_s v_s} V\right), \quad (3)$$

where C is mass concentration, σ , v_s and ρ_s characterise the particle and V represent the ensonified volume which is a function of R . Combining equations 1, 2 and 3, we can write (Tessier, 2006):

$$10\log_{10}(C) = RL - SL + 20\log_{10}(\Psi R) + 2\alpha_w R - 10\log_{10}(V) - 10\log_{10}\left(\frac{\sigma}{\rho_s v_s}\right) \quad (4)$$

Usually this equation is calibrated with independent measurements of sediment concentration including unknown terms in linear regression constants (Gartner, 2004).

Here our independent concentration measurements with the LISST are insufficient or unusable with bubbles to calibrate equation 4. Thus we consider the same kind of particles, bubbles, present overall the water column. These bubbles produce the recorded backscatter allowing to define a reference level at a given depth and, using equation 4, permit to define a reference concentration. Subtracting this reference concentration to equation 4, we can write a dimensionless form of equation 4:

$$10\log_{10}\left(\frac{C}{C_0}\right) = RL - RL_0 + 20\log_{10}\left(\frac{\Psi R}{\Psi_0 R_0}\right) + 2\alpha_w (R - R_0) - 10\log_{10}\left(\frac{V}{V_0}\right) \quad (5)$$

in which subscript 0 denote reference quantities. Equation 5 enables to avoid two unknown terms in equation 4: one linked to particles response to an acoustic impulse and the other linked to the source level.

To apply this backscatter processing, we first select a bubble cloud (typically between 45 and 55 minutes in Fig.2). Then we find the maximum of backscatter to define the reference level. Finally we apply transmission loss and ensonified volume corrections to obtain concentration ratio (equation 5).

4 LATERAL TURBULENT DIFFUSION MODEL

River turbulent motions are known to have a diffusive behaviour. Along the lateral direction (perpendicular to the mean flow) the approximation of a negligible mean lateral flow velocity component can be done and thus turbulent diffusion can be written as (Rodi, 1993):

$$\frac{\partial C}{\partial t} = \frac{\partial}{\partial y} \left(\lambda \frac{\partial C}{\partial y} - \overline{(v')C'} \right), \quad (6)$$

where λ is the molecular diffusion which is assumed to be negligible and $\overline{(v')C'}$ is linked to the concentration gradient along lateral direction (Taylor, 1953). Using these considerations the previous equation leads to:

$$\frac{\partial C}{\partial t} = \epsilon_y \frac{\partial^2 C}{\partial y^2} \quad (7)$$

where ϵ_y is the lateral turbulent diffusion constant which with a dimensional approach can be expressed as $\epsilon_y = \alpha u^* H$ where u^* is the bed shear velocity, H the river characteristic water depth and α the dimensionless lateral mixing coefficient (Fischer & Park, 1967; Bouchez et al., 2010). This equation is non-dimensional, with $C^* = C/C_i$, $y^* = y/w$ and $t^* = \epsilon_y w^2 t$, to:

$$\frac{\partial C^*}{\partial t^*} = \frac{\partial^2 C^*}{\partial y^{*2}} \quad (8)$$

where C_i is the injected concentration and w the width of the river.

5 RESULTS

Equation 8 was numerically solved with concentration boundary conditions fixed to zero at each river banks (i.e. $C^*=0$ at $y^*=0$ and $y^*=1$). Assuming the localisation of the bubble source behind the ship propeller, we use a concentration impulse at this position as an initial condition. To find the best lateral turbulent diffusion coefficient, we first calculated the bed shear velocity by fitting the vertical velocity profile recorded by the ADCP, using the law of the wall. Then we minimised the α parameter with the depth-averaged concentration (Fig.4). We obtained $\alpha=17.1$, equivalent to $\varepsilon_y=1.8 \text{ m}^2.\text{s}^{-1}$ with $u^*=0.07\text{m}.\text{s}^{-1}$ and $H=1.5 \text{ m}$.

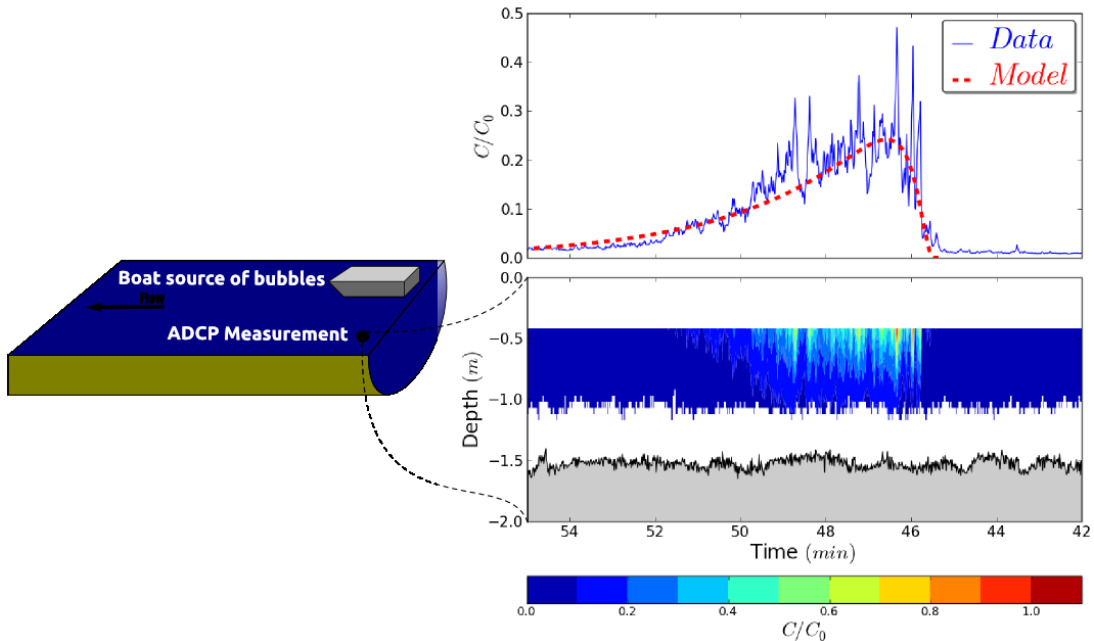


Figure 4 Result of lateral turbulent diffusion model against relative concentration from ADCP backscatter measured near Sully bridge. On the left: a cartoon representing the measurement situation. On the right: the bottom part of the plot shows the relative concentration with respect to depth and time while the upper part is depth-averaged backscatter (in blue) and the result of the turbulent diffusion model (in red)

This simple model gives reasonable results and reproduces well the shape of concentration signal. The resulting value of lateral mixing coefficient is similar to the one found by Bouchez et al. (Bouchez et al., 2010) on the Amazon river: $\varepsilon_y=1.8 \text{ m}^2.\text{s}^{-1}$, with $u^*=0.05 \text{ m}.\text{s}^{-1}$ and $H=25\text{m}$. In literature the dimensionless transverse mixing coefficient, α , varies over a large range from 0.1 to 3.5 (Rutherford, 1994). Compared to these values, the Seine transverse mixing coefficient is very high and may reflect effects of ship propellers rotation on mixing efficiency.

6 CONCLUSION

For the Seine river, in Paris city, ADCP and LISST measurements show essentially the presence of bubbles produced by ship's propellers. Their effects in recorded signals have to be taken into account in order to realise a fair estimation of sediments concentration with these instruments. Nevertheless, bubbles can be successfully used to estimate lateral turbulent mixing coefficient in this river. Here, this estimation leads to a high value of lateral mixing coefficient. Using a distance criterion, based on lateral turbulent

mixing coefficient, we can infer an homogenisation distance (Bouchez et al., 2010):

$$d \ll \frac{W^2}{\epsilon_y} \times \overline{u} \quad (9)$$

During low discharge period, the Seine typical mean velocity is around $0.3 \text{ m}\cdot\text{s}^{-1}$ and his typical width is around 100 m. With $\epsilon_y=1.8 \text{ m}^2\cdot\text{s}^{-1}$, equation 9 gives an homogenisation distance of 2 Km. With this value, we argue that high frequency turnover of tourist boats may prevent sediments deposition during low water discharge period. Measurements of sediment concentration and sediment plume produced by boats outside of Paris city can help to constrain this hypothesis. Furthermore, other measurements using bubbles signal recorded by ADCP are required to constrain lateral turbulent mixing coefficient in the Seine river and ascertain the influence of boats turnover on the mixing coefficient.

7 ACKNOWLEDGEMENT

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